

PLACE-MAT 360 OPERATION MANUAL

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	ECIFICATIONS 2
	Section
APPLICABLE ASSEMBLY BOARDS	 Board Measurements X 300mm (max) 30mm (min) Manual Set 330mm (max) 30mm (min) when using automatic conveying x 250mm (max) 30mm (min)
	 t 2.3mm (max) 0.6mm (min) 2. Position Fixing Method Hole or Perimeter Standard (See Fig. 2-1).
	3. Top/Bottom Height Limits for Assembly Board Parts (See Fig. 2-2)
	4. Allowable Warp of Boards Paper Phenol Up/Down 1mm Glass Epoxy Up/Down 1mm Alumina Ceramic Up/Down 0.2mm
	 Board Setting Method Manual Set (With automatic conveyor, automatic)
	6. Board Width Adjustment Method Manual
MOUNTING HEAD	1. Mounting Accuracy ±0.2mm
	 Mounting Angle 0°, ±90° (However, with rotary table can be mounted every 15°)
	3. Mounting Head Repetition Accuracy ±0.1mm
	 Mounting Timing Interval 1.2 seconds, minimum
	5. Head Movement Speed 450mm/second

6. Number of Heads

1 head

7. Number of Bits

4 types, interchangeable to fit various parts For small chips For medium chips For large chips For QFP

8. Operational Air Pressure 5 kg/cm² (Dry air)

9. Operational Air Consumption Within 60NI/min



3.

PARTS AND PARTS PACKING

Table 2-1

Parts							Par	ts P	acki	ng 🕯	٤3						E	Bit *	3	_
						Та	pe					BU	ST	то	MG					
	Width Pitch	8 4	12 4	12 8	16 4	16 8	16 12	24 12	24 16		32 12					1	2	3	4	5
Square (Chip 2125	0										0				0				
	3216	0										0				0				
	3819	0														0	0			
	4726		0														0			
	6332			0													0			
	7343			0													0			
MELF	1/16W	0									100	0				0				
	1/8W	0										0				0				
	1/4W			0								0				0	0			
Mini-mo	rd Transistor	0													0	0	-			
Mini-pov	wer Transistor			0											0		0			-
Mini-flat	IC 8P			0		0					0		0					0		
	14P					0	0				0		0					0		
	16P					0	0				0		0					0		
	20P							0			0		0					0		*
	24P							0			0		0							c
	28P							0	0		0		0						*1	c
PLCC	18P							0					0							C
	20P						0	0					0							c
	28P							0	0				0						*1	c
	32P							0	0				0						0	
	44P												0						0	
	52P												0						0	
	68P												0			-			0	
QFP	(44~64P)				-			-					-	0				1	0	

* 1) When the size of the element is 11.4mm or larger, use a No.4 bit.

* 2) When the width of the resin part is 6 mm or larger, use a No.5 bit.

* 3) BU: Bulk Bit type 1: for small chips

ST: Stick	2:	for medium chips	
TO: Tray	3:	for SOP (small)	
MG: Magazine	4:	for PLCC	
	5:	for SOP (large)	

Load pitch for mini-flat IC, PLCC, and QFP: 1 mm or more

Maximum kinds of parts that can be loaded: 88

Supply Direction: Front, Rear, Left, Right (depending on how parts are packed)

* Parts other than the above may be used providing specifications are compatible.

CONTROL EQUIPMENT

1. Axis Control Method Open Loop by Pulse Motor

- 2. Data Input Method Teaching and MDI
- 3. Minimum Specification Range 0.1mm
- 4. Maximum Mounting Points 2000 Points
- 5. Vacuum System Error Detection Method Pressure Sensor
- Control Equipment
 8-bit Computer (5-inch floppy disk, double-disk drive)
- 7. Operation Modes Production Mode (Continuous or Step) Teaching Mode Data Input Mode

1. External

670mm(W) x 750mm(D) x 280mm(H) (Main unit cover only)

2. Weight 62kg (Main unit only)

3. Voltage 100V±10% 110V, 120V

220V, 240V Selectable Specifications

4. Power Consumption

450VA (main unit) 750VA (maximum when using options)

5. Frequency

50/60Hz

6. Environment

Working	Temperature	5 to 40°C
	Humidity	10 to 80%
Storage	Temperature	-20 to 60°C
	Humidity	10 to 90%
industry Vice		

The above specifications do not apply to the persona computer.

Also, they apply only when there is no condensation.

5..

GENERAL SPECIFICA-TIONS

6			
•	~	отіс	

Lateral Magazine Tray Unit Number 4 per unit Maximum Loading Units 2 units Bulk Feeder Unit Number of Lanes 10 lanes p Maximum Loading Units 8 units

Number of Parts Receivable

10 lanes per unit 8 units 3,000 per hopper (max) (However, the maximum number varies depending on the chip. For 1/4W MELF, the maximum is 100 to 150.)

3. Tape Feeder Unit

 8/12mm Tape Feeder Unit Tape Reel Specifications:

Number of Tape Cassettes:6 cassettes per unitMaximum Loadable Units:6 unitsTape Width:8, 12mmTape Feeding Pitch:4, 8mmCompatible Reel Diameter:178mm

 32mm Tape Feeder Unit Tape Reel Specifications:

Number of Tape Cassettes:6 cassetMaximum Loadable Units:6 unitsTape Width:32mmTape Feeding Pitch:12mmCompatible Reel Diameter:382mm

 16/24mm Tape Feeder Unit Tape Reel Specifications:

Number of Tape Cassettes:4 cassettes per unitMaximum Loadable Units:4 unitsTape Width:16, 24mmTape Feeding Pitch:4, 8, 12, 16, 20mmCompatible Reel Diameter:178, 330, 382mm

Conforms to EIAJ Standard, RC1009 6 cassettes per unit 6 units 8, 12mm 4, 8mm 178mm Other diameters require special arrangement.

Conforms to EIAJ Standard, RC1011 6 cassettes per unit 6 units 32mm 12mm 382mm Other diameters require special arrangement.

Conforms to EIAJ Standard. RC1009 4 cassettes per unit 4 units 16, 24mm 4, 8, 12, 16, 20mm 178, 330, 382mm Other diameters require special arrangement.

4. PWB Receptor

Applicable Assembly Board Dimensions

Х	300mm (max)	30mm (min)
Y	250mm (max)	-30mm (min)
t	2.3mm (max)	0.6mm (min)

5. Automatic Conveyor Unit for Assembly Boards

Applicable Assembly Board Dimensions X 330mm (max) 30mm (min) Y 250mm (max) 30mm (min) Assembly Board Progression Right to left, or left to right

(Determined at time of shipping)

6. Rotary Table Unit

Mounting Angle Every 15° Perimeter Dimensions of Mounting Area

Within 25.6mm x 25.6mm Lead Pitch 1mm or more

7. Stick Feeder Unit

PLCC Stick Feeder Unit

Standard Type
 Number of Lanes
 Maximum Loadable Units
 Compatible Stick
 Diamensions
 2 lanes per unit
 5 units
 Width: 10.5 to 15mm
 Height: 4.5 to 10mm
 Length: 175 to 600mm

Compatible Parts

 Wide Type Number of Lanes Maximum Loadable Units Compatible Stick Diamensions

Compatible Parts

Length: 175 to 600mm Any length beyond 600mm requires special arrangement PLCC 18, 20, 28 or 32 pins Compatible part dimensions are listed in the table 1 lane per unit 5 units Width: 10.5 to 15mm Height: 4.5 to 10mm Length: 175 to 600mm length beyond Any 600mm requires special arrangement PLCC 18, 20, 28, 32, 44, 52 or 68 pins Compatible part dimen-

sions are listed in the table

No. of Pins	w: Width [mm]	I: Length [mm]	t: Thickness [mm]
18	8.0 to 8.5	13.0 to14.0	3.1 to 4.0
20	9.5 to 10.0	9.5 to10.0	4.0 to 5.0
28	12.1 to 12.6	12.1 to12.6	4.0 to 5.0
32	12.1 to 12.6	14.5 to15.5	3.1 to 4.0
44	17.2 to 17.7	17.2 to17.7	4.0 to 5.0
52	19.7 to 20.2	19.7 to20.2	4.0 to 5.0
68	24.9 to 25.4	24.9 to25.4	4.0 to 5.0

Any dimension not listed in the table above requires special arrangement.

8. IC Tray Unit

Maximun Loadable Unit Compatible Parts External dimension of elements Compatible Tray Diamensions 1 unit QFP. PLCC

11.4 to 25.6mm per side Width: 130 to 146mm Length: -314 to 319mm Height: 9mm or less Other dimensions require speial arrangement

9. Dispenser Unit

Dispenser Unit

Control method	Pneumatic electronic control
Pressure adjustment range	0.1 to 0.7kgf/cm ²
Power consumption	7VA or more
Timer	0.001 to 9.999 sec Digital setting in 1ms Units; Quartz timer (Can be internally switched in a renge of 0.01 + 99.99 seconds)
Operating perfomance (Controller)	400 operations/min.
Vacuum mechanism (Controller)	Built-in
Syringe capacity	10cc
Metallic needle	Provided with S18, S20 (made by Uni-controls), or any corresponding part.
Compatible materials	Adhesive for chip parts Cream solder (for dispenser)

• Thermostat for Dispenser

Range of temperature	0 to 99.9°C Digital setting in 0.1°C units			
Control method	Time-ratio control			
Heat control power	Max 700W (separate transforme	r provided)		
Usable voltage	AC100V 50/60Hz			
Thermostat syringe	Recommended operating range Temperature sensor Compatible syringe	Max 50°C Platinum 10cc		

10. Special desk

Size

Width: 670mm Depth: 750mm Height: 735mm 1195mm (Up tp CRT base) 60kg

Weight

* Main specifications subject to change without notice upon improvement.



1. Front View



2-9





1. _____ MAIN UNIT, FRONT



- Power Switch When this is turned on, power is supplied to the main unit.
- ② Home Switch When this is turned on in the teaching mode, the head moves, and stops at the starting point (home position).
- (3) Emergency Stop Switch Press this switch to stop the machine in an emergency.
- Connectors (for feeders)
 Connect power cords from these connectors to each feeder on the front of the base.
- (5) Fuse (3A)

2. EXPLANATION OF

OPERATION PANEL



1 HEAD Switch

When in teaching mode, or for an I/O test, press this switch to move the head bit up and down.

② Vac (Vacuum) Switch

When this switch is pressed in teaching mode, or for an I/O test, the head is in "vacuum" position, ready to pick up an assembly board.

③ TEACH Switch

If this is pressed in the teaching mode, the current XY coordinates will be input for the head position.

(4) $\leftarrow \rightarrow \uparrow \downarrow$ Switches

The head moves in the direction of the arrow.

(5) FAST Switch

The speed of the head movement increases when this switch is pressed while holding down switch (4).



3. Main Unit and Controller Connections

- Make sure power to the placer main unit, controller, CRT display, and all other mechanisms is turned OFF.
- 2. Connect the cord of the keyboard (1) to the keyboard connector (2) on the front of the controller.
- 3. Connect the CRT cable to the (Digital RGB) CRT connector ③ of the controller. Connect the other end to the connector on the rear panel of the display.
- 4. Connect the power cord of the display to the AC 100V connector ④ of the controller.
- Connect the two signal cables to the corresponding extension board connectors (50, 36 pins) (5), and fasten the other ends firmly to the connectors (6) of the main unit.
- 6. Also connect one end of the power cord of the controller to the AC <u>connector</u> (2) on the rear panel of the controller, and the other end to the connector (8) on the rear panel.
- 7. Connect the power cord to the power connector (9) of the main unit.
- The switches of the front panel of the controller should be set as follows: Operation Clock Switch (1) 8MHz
 - System Mode Switch (1) V2

2. Connecting the Air System Parts Please refer to Fig. 2-4.



- For air supply (dry air), use an accessory air hose (ø8 tube) and attach it to the Air Intake ①.
- 2. Raise the filter regulator (2) knob in the direction of the arrow as shown in Fig. 3-4 and rotate it clockwise. When the air pressure reaches 5 kg/cm² lower the knob.
- The air piping of the various feeders is connected as outlined below. Air opening of the feeder (ø8 tube)(3)......Dispenser Unit Air opening of the feeder (ø6 tube)(4)......Tape Feeder Unit Air opening of the feeder (ø4 tube)(5)......Rotary Table Unit, Automatic Conveyor Unit

NOTE:_

When making connections, make sure that you put any removed caps/covers in safe places so they are not lost.

3. Connecting Option Attachments

Diagram of Option Attachment Positions



Attach- ment Position	Option	Attach- ment Position	
F1		то	IC Tray U
F2 B1	Tape Feeder Unit	B3	Rotary Ta
B2	Bulk Feeder Unit	A1	Assembly
L1 L2		AB1	Assembly Backup P
R1 R2	Bulk Feeder Unit	AB2	Assembly Backup P
Р	PWB Receptor		- additup :
M1 M2	Lateral Magazine Tray Unit	NOTE: • Whe	n attachin
ST1 ST2 ST3 ST4 ST5	Stick Feeder Unit	the l • Whe unit	first turn of head so it in an assen is attache s L1, L2, F

Attach- ment Position	Option			
T0	IC Tray Unit			
B3	Rotary Table Unit			
A1	Assembly Board Automatic Conveyor Unit			
AB1	Assembly Board Automatic Conveyor Unit Backup Pin Base (right to left)			
AB2	Assembly Board Automatic Conveyor Unit Backup Pin Base (left to right)			

- When attaching any of the options, make sure you first turn off the power switch. Then move the head so it doesn't get bumped or struck.
- When an assembly board automatic conveyor unit is attached, the option attachment positions L1, L2, R1 and R2 cannot be used.
- The tape feeder unit of 16mm or 24mm tape width cannot be mounted using positions L1 and L2.
- When a 16/24mm tape feeder is installed in F1, and F2, the Lateral Magazine Tray Unit cannot be installed in M1. The same is true regarding M2 when B1 and B2 are being used.



1. Attaching to the Main Unit (See Fig. 3-5, page 3-5.)

Insert Position Fixing Pin B (6) into the hole in the main unit as shown in Fig. 3-6, and secure the bolts (M5 x 10), using the wrench provided. Next, fasten Bracket F (7) to the base (5) of the PWB Receptor with a bolt (M5 x 10), using the wrench provided. Attach Bracket B (8) and the Center Bracket (9) by inserting the PWB Receptor Nut (2) into the slot on the base (5) from the back and secure it by turning the handknob (1) tightly.

2. Adjusting the Width

When changing the size of the assembly boards, the PCB Receptor Bracket B (8) must be moved back and forth until it matches the width of the board. Loosen the two handknobs (1) and set the new position for the assembly board width.

3. Aligning the Position Fixing Pin

Loosen the bolt ④ holding the PWB Receptor Pin B ① and realign it to fit in the hole on the assembly board.

4. Aligning the Backup Pin

When the assembly board is large, the pressure between the bit head (when down) and the backup pin (3) keeps the board from curling. Loosen the two handknobs (1) and the center pins (3), and set the board in position so that the backup pin is not touching any of the parts on the assembly board.



1. Attaching to the Main Unit (See Fig. 3-5, page 3-5.) Attach the two handknobs (1) to the fixed knock pin holes on the base. (See Fig. 3-7) At this time, attach the magazine pusher (2) to the right.

2. Connecting and Disconnecting the Magazine

Insert the magazine from above, into the slot of the Magazine Guide ③ which is attached to the Magazine Pusher ②. Then attach it to the opposite Magazine Guide ④. Make sure the end side of the magazine and the reverse end side of Magazine Guide ④ are touching securely. To remove the magazine, insert your finger in the hole of the magazine bracket ⑤ and push up on the magazine.

3. Pass the L-shaped end of the wire (6) through the notch of the wire holder (7) from the inside. (Fig. 3-8-a)

Insert the wire (6) between the magazines, and push down on the magazines (so that the V-shaped wire is positioned downward and the projections hold down both magazines.)

Slide the wire (6) slowly in the direction of the arrows shown in the figure, unit the L-shaped end of the wire (6) is stopped at the notch of the wire holder (7). (Fig. 3-8-b.)

NOTE:

When the wire is installed, make sure that both magazines have already been installed.



3-8





 Attaching to the Main Unit (See Fig. 3-5, page 3-5.) Attach the bulk feeder unit to the fixed knock pin holes of the main unit, and secure it with the 2 handknobs(1).

2. Exchanging the Alignment Blocks

Exchange the alignment blocks of the end sections to match the dimensions of the parts. First, remove the cover from the end section ③. Next remove the two screws ② and pull the blocks toward you to remove them. Line up the new blocks with the hole in Tray A④ and insert them. Secure the end section stopper ⑤ with the screws ②. Next, press the end section cover ③ into place from above in a position such that the distance between the cover and the end stoppers is slightly longer than the length of the parts dimensions. The dimensions of the slot into which the blocks are fit are as shown in Fig. 3-10.



Layout of Bulk Feeder Lineup

3-10

Mar

Sec. Sr. Ar



See See



Table 3-1

(Unit: mm)

¢

Part Name	Symbol	н	h		1
Alignment Block A	3216 A	1.35	0.8	1.85	+0.1
Angliment block A	2125 A			1.5	
Alignment Block B	3216 B	1.05	0.65	1.85	
Alighment block b	2125 B			1.5	
Alignment Block C	3216 C	0.7	0.4	1.85	0
Alighment block C	2125 C	0.6		1.5	
		2.5	2	2.5	
Alignment Block E		1.5	1	1.5	

ĸ.

3. Connecting the Power and Adjusting the Control Box



Connect the power cord to the main unit at the connector for feeder use near the bulk feeder unit (see Figs. 2-4, 3-1, pages 2-7 and 3-1 respectively).

Open the plastic cover ④ by pulling it toward you. When the proper amounts of parts have been loaded onto each tray, close the cover and rotate the vibration adjustment knobs of the hopper ② and feeder ③ counterclockwise to the "Minimum" position (to avoid vibration). Turn on the power switch ①.

Rotate the vibration adjustment knob clockwise until the optimum position has been found.

NOTE:

Vibration may result, depending on how the adjustment is made. Please adjust the knob carefully to avoid vibration. Also, the amount of variation may change if large and small elements are sent together. In a case like this, re-adjustment may be necessary. If the elements of an alignment block are out of alignment, replace or supplement the elements.



a) Tape Feeder



b) Tape Cassette Attachment Assembly



2. Attaching the Tape Cassette Attachment Assembly



- 1. Fasten the attachment assembly to the base using the 2 handknobs (1), as in Fig. 3-13.
- Remove the cap from the air opening for feeders on the back of the main unit, and plug in the air hose (ø6 tube) (2). (Use the filter regulator (2) shown in Fig. 3-4 to set the air pressure to 0.)
- Attach the power cord to the connector (for feeders) on either the front or rear panel of the main unit.
 Please check first that the power to the main unit is OFF.



At the same time that the work on the carrier tape of the tape feeder (whose position is determined by the knock pins on top of the main unit), is being held by the vacuum bit (1), the knock load (2), which is equipped with the head, presses the knock SH of the tape feeder.

After the bit which held the work by vacuum has lifted, the knock SH returns, and the tape advances one pitch.

5)

4. Handling

- 1) Attaching the Taping Reel
 - a) First the tape width is determined. Specify the width at the back of the guide blocks (1).



b) Next, the tape pitch is determined. Rotate the block for changing the pitch (1) 180°.





- d) Open the front cover (4) towards you, and open the work cover (5).
- e) Draw out the tape from the reel, and, following the guide, align the hole in the carrier tape with the pin of the wheel (6).
- f) Hook the cover tape to the cutaway section of the work cover (5), and stick the tape to the reel curler (7) that was taken off from the main unit. After the tape has been stuck onto the reel curler, replace the reel on the main unit, return the work cover (5) to its original condition, fixing it in place with the front cover (4), and rotate Tape Holder A (8) clockwise to take up any slack in the cover tape.



- g) Rotate the cylinder (1) by hand and make sure that both the carrier tape and the cover tape are advancing. Advance the carrier tape until it reaches the middle of the discharge guide (2).
- h) When using 8mm-pitch tape, confirm the center. There is no need for confirmation when using 4mm-pitch tape, but when using 8mm-pitch tape, adjust the position of the pitch switch block so that the center of each part comes to the center of the front cover (3) and the work cover (4) window.



- 2) Attaching the Tape Cassette Assembly
 - a) Insert one end of the position fixing shaft of the tape cassette assembly into the U-shaped slot on the front side of the feeder. Next, insert the other end of the shaft into the rear side of the attachment assembly.
 - b) Remove the caps from the piping joints of the top/front cover box and insert the air hose (ø4 tube) of the tape cassette assembly.
 - c) Insert the tape cassette assembly connector into the connector of the top/front cover box.
 - d) Rotate the hand valve in the ON direction to supply air.
 - e) Press the knock SH pin lightly with your fingertip to advance the carrier tape until the work comes to the bit position.

3) Removing the Tape Cassette Assembly



- a) Rotate the hand valve knob (1) 90° to shut off the air supply.
- b) Disconnect the feeder connector from the control box.
- c) Remove the air tube of the feeder from the control box.

NOTE:_

To remove it, push up on the plastic section of the piping joint and pull the tube off.

d) Pull the feeder towards you while lifting it up.

5. Reversing the Left and Right of the TF Cover Box

When two tape cassette assemblies have been attached next to each other, if the TF cover box is not attached with right and left reversed, it cannot be connected to the main unit. When right and left are attached in the same position, change one of them as shown in the diagram below.



With the wrench provided (M4), remove the 2 screws (M4 x 10) holding the box(), and connect it to the back support () opposite.

8. _____ REPLACING THE BIT

For bit replacement, refer to Table 2-1 (page 2-3) for the bit that matches the parts size.



To remove the bit, when the message "Change the Bit" appears on the CRT display, the head moves to the right side of the machine nearest you, and stops. Take hold of the slot in the end of the bit (1) with your fingers and pull the bit downwards while rotating it. To attach the bit, push the bit (1) up through the hole of the pin hold (2) and rotate it until it clicks.

INSPECTION

9.

Before starting operation, check to make sure that water has not collected in the filter regulator.

If it has, press up on the notch ① with your finger as shown in the illustration below. Lay a cloth or something under the drainhole so that water doesn't drip into the main unit.


10.

Parts to be Lubricated	Oil Supply Period	Usable Grease
 Guideshaft A Guideshaft B Guideshaft C Guidebar 	Once every 6 months	A good-quality No.2 grease with a lithium soap base or similar grease
(4) Head	1 or 2 drops/week	Tufoil (accessory)

REMOVING THE COVER



- Guideshaft A Remove the two screws (M3 x 8) and open the RT cover.
- ② Guideshafts B and C Remove the six screws (M3 x 6) and take off the bail cover.
- ③ Guidebar Remove the seven screws (M3 x 8) and take off the LT cover.

NOTE:_

Be careful not to get grease on the belt pulley or the belt.

(4) Head

Be sure to lubricate the locations shown in Fig. 3-27 when work is finished. When lubricating before you start work, or operating immediately after lubrication, push the knock cap down to the bottom 4 or 5 times ensure good oil penetration.



ADJUSTING THE PRES-SURE SENSOR

- (1) First, adjust the air pressure of the filter regulator to 5 kg/cm².
- (2) Change the bit to 1.
- ③ Set the unit to the head check of the I/O test mode, lower the bit, and set the vacum to ON. At this time, before the parts have been mounted, adjust the volume so that the red lamp illuminates.
- Next, turn the volume knob to the right until the red lamp goes out. (Be careful not to turn it too far.)
- (5) Using MELF 1/8 W, set the re-try. Be sure to confirm that the re-try function is operating properly. If you are not using MELF, check this with a square chip.





The set-up procedure of the system is described as follows:



*1.....Insert the system disk in drive 1, and the data disk in drive 2.

*2.....Upon initialization, the following two programs are run automatically.

KBIOS..... program for displaying Japanese.

PK1INIT...... contains the program for XY motor control and rotary table control, and also initializes the I/O ports and the XY motor controller IC.

PC-8801 FH Switch Setting

The front panel switches of the PC-8801 are shown next.



1	Operation Clock Switch	8 MHz
2	System Mode Switch	V2



When the setup process is finished, the following main menu screen is displayed.

(Screen 5-1 / Main Menu)

	Main Menu
1 .	Feeder Coordinate In
2 .	Placement Data In
3.	Product
4 •	Test
5.	Sub Operations
/ •	End
	Select No.

OUTLINE

1.

The following items are activated depending on which selection is made, from items 1 to 5, or /.

- Unit Data Input determines unit specifications, as well as defining the supply position of parts.
- 2. Mount Data Input determines the loading position of parts, based on the unit data.
- 3. In the production phase, bonding and paste solder are applied to already positioned assembly boards, and parts are inserted on them.
- 4. The test phase is divided into 5 parts covering Input Check, Head, XY Movement, Rotary Table, and Automatic Conveyor. This function tests the operation of the driver simplex and checks the I/O port signals, etc.
- Auxiliary Operations covers input of the cement pattern and parts data as well as data file deletion.



(Screen 6-1 / Unit Data Input)

** Feeder Set **

100

	B1(*)	B2	B3	Filename	MANUAL	(12/12)
	Stick	Stick	R.T	Key f·1: Load File f·6: Save	Operations ESC : Data I / : End	n
L2(*) Tape (3)	M2(*) Magaz.		R2	Feed	ler No.	
	PWB		ןן	 Linear Fee Tape Feed Tape Feed 	er/ 6 (Tape (6))	
L1(*) Tape] <u> </u>	,	R1(*) Linear	 Tape Feed Stick Feed 	er/ 3 (Tape (3)) er (Stick)	
(6)	M1(*) Tray			 Magazine IC Tray Rotary Ta 	(Magaz.) (Tray) ble (R.T)	
	F1	F2		0. Delete Select No.		

NOTE:__

- 1. The bulk feeder is indicated as the linear feeder at the top of the screen.
- 2. An asterisk (*) is displayed to the right of the unit position when feeder information for the unit has been specified.

1. _____

To specify a unit in a unit specification position, move the cursor to the position of the unit that you want to specify and press the number of the unit. The correspondence table is shown below.

Table 6 1

(Items marked with a C) indicate that specification is possible.)

Unit Position	Bulk Feeder	Tape Feeder	Stick Feeder	Magazine	IC Tray	Rotary Table
F1	0	0			•10	
F2	0	0			·10	
B1	0	0	0			
B2	0	0	0	7		
B3			0	-		0
R1	0					
R2	0					
L1	0	0.2				
L2	0	0.2				
M1				0.3	•10	
M2				0.3		

^{*1}......When using an IC Tray, F1, F2, and M1 can all three be accessed. However, only M1 will be set and displayed; F1 and F2 are not fully displayed.

*².....Setting cannot be performed in the case four tape feeders (of 16mm or 24mm type) are installed.

*³......When a 16/24mm tape feeder is installed in F1, and F2, the magazine cannot be installed in M1. When the feeder is installed in B1, and B2, the magazine cannot be installed in M2.

1. Explanation of Key Operations (Functions Shown in Screen 6-1)

[f·1]	This is used to call a data file from a disk.
(Load File)	If the $f\cdot 1$ key is pressed, the file directory will be displayed. Input either the number or the name of the file you want. If you want to abort the operation, press $f\cdot 1$ again.
[f·6] (Save)	This is used to save input data on a disk. If the f.6 key is pressed, the file directory will be displayed. Input either a number (1 to 12) or a name for the file you want to save. The name can be up to 8 letters (English alphabet). If you specify a number other than 1 to 12, the number will be stored as the file name, so be careful to store a valid number. If you want to abort the operation, press f.6 again. Up to 12 files can be stored.
ESC	When you want to specify the feeder coordinates after specifying a
(Data Input)	unit, move the cursor to the target unit position and press ESC. The screen switches to the Feeder Coordinate Input screen.
[7]	Press to terminate.
(End)	When this key is pressed, the message "Do you want to save? (Y/N) " appears. To save, press "Y"; otherwise press "N". If a different key is pressed, the operation will continue without being terminated.
NOTE:	
f·1, f·2 f·	10) are function keys.



After specifying a unit, the parts supply positions of each unit (in the case of a linear feeder, 10 places) are specified here. Saving the specifications is done on the unit specification screen. In the illustrations below, the coordinates specification screen for each individual unit is shown, followed by a chart of the operations.



NOTE:__

As shown at the left, the rail numbers of each unit are organized with the rail nearest the starting point being the lowest number.

1. Explanation of the Screen (a) Bulk Feeder Unit

	Feeder	Pos.: R1	Feede	r: Lin	ear]	
No.	Kind	Comp. Data	Size	Bit	X mm	Ymm
1	****	1: 2125	2.0	1	356.1	145.5
2	****	2: 3216	3.2	1	356.7	159.5
3	••••	3: MLF16W	1.6	I	355.9	173.5
4	****	4: MLF8F	2.0	1	356.1	187.5
5	****	5: MLF4F	5.9	2	358.0	201.5
6	****	:				
7	****	1				
8	****					
9	****	1		_		
10	****	:				

Filename	MANU	UAL
Bit Pos.	$\mathbf{X} = 2$.4 Y = 429.6
Key (Operations	
f·1:Load File	f•4 :E	Delete
f·2:Teach/B	ESC:C	Compo.Tbl.
f•3 : Teach/S		ind
No. Name	Size	Bit
: 2125	2.0	1
: 3216	3.2	1
: MLF16W	1.6	1
A : MLF8W	2.0	1
5 : MLF4W	5.9	2
5 : SOP8P	6.0	3
7 : SOP16P	12.5	3
lo:		
No. or Name		

(Scroon 6.2)

* One unit has 10 bulk feeders. The input data consists of the Parts Data (which is input by number and name or by bit) and the X-axis and Y-axis coordinates (which are input by MDI or by teaching). Teaching is also performed in case fine adjustments are performed. As you can see in the righthand side of Screen 6-2, when you press the ESC key, parts data can be displayed 8 items at a time (32 altogether).

NOTE:

For information on selecting the corresponding bit for a part, please refer to Section 6-3, "Bit No. Specification."

b) Tape Feeder Unit [Feeder Pos.: L1 Feeder: Tape (6)]

No.									
NO.	Kind	Comp. Data	Size	Bit	X mm	Y mm	Filename Bit Pos.	$MANU \\ X = 2$	JAL 4 Y = 429.6
1	8mm	1: 2125	2.0	1	0.1	142.5	Key Ope		
2	8mm	2: 3216	3.2	1	0.1	164.0	f-1:Load File	f•4 :E	0.0000000000000000000000000000000000000
3	12mm	5: MLF4W	5.9	2	0.1	187.3	f·2:Teach/B f·3:Teach/S		Compo.Tbl. End
4	12mm	3		2	0.1	208.8			
5							No. Name 1 : 2125	Size 2.0	Bit
6							2 : 3216	3.2	i
					1	+	3 : MLF16W 4 : MLF8W	1.6 2.0	1
					-	<u> </u>	5 : MLF4W	5.9	2
					-		6 : SOP8P 7 : SOP16P	6.0 12.5	3

One unit may have either three tape feeders (of 32mm tape width), four tape feeders (of 16mm or 24mm tape width), or six tape feeders (8mm or 12mm tape width). In case of six or four feeders, the input data consists of the "Type," "Parts Data" (input of only the bit is also permitted), as well as the X-axis and Y-axis coordinates (which are input by MDI or by teaching). In case of three feeders, the input data consists of the "Parts Data" (input of only the bit is also permitted) as well as the X-axis and Y-axis coordinates (which are input by MDI or by teaching). In case of three feeders, the input data consists of the "Parts Data" (input of only the bit is also permitted) as well as the X-axis and Y-axis coordinates (which are input by MDI or by teaching). Note that "Parts Data" can ordinarily be input by the number and name or by the size and bit. During teaching, the Up/Down movements of the bit on the tape element may cause elements to jump or be skipped; therefore, make sure to perform fine adjustments where there are no elements and, as the last step, make sure the elements are positioned below the bit.

NOTE:

For information on selecting the corresponding bit for a part, please refer to Section 6-3, "Bit No. Specification."

c) Stick Feeder Unit [Feeder Pos.: B1 Feeder: Stick (S)]

No.	Туре	Parts Data	Size	Bit	X mm	Y mm
1	STD.	6: SOP8P	6.0	3	19.5	495.3
2	STD.	6: SOP8P	6.0	3	51.5	495.3
3	WIDE.	7: SOP16P	12.5	3	100.5	498.5
4						-
					-	

Filename	MANU	DOI TRANSFORMENT AND
Bit Pos.	X = 2	.4 Y = 429.6
Key	Operations	
f·1:Load File	f•4 :E	Delete
f·2:Teach/B	ESC:C	Compo.Tbl.
f-3:Teach/S		Ind
No. Name	Size	Bit
1 : 2125	2.0	1
2 : 3216	3.2	1
2 : 3216 3 : MLF16W	1.6	1
4 : MLF8W	2.0	1
5 : MLF4W	5.9	2
6 : SOP8P	6.0	
7 : SOP16P 8 :	12.5	3
8 :		
1:STD. 2:WID	E	

(Screen 6-3)

* Based on the dimensions of the parts, one unit may consist of two standard-type stick feeders or one wide-type stick feeder. Two units can be set at the unit positions B1 and B2, whereas one unit can be set at unit position B3 (a maximum of 10 stick feeders can be loaded). The wide-type stick feeders can only be set to No. 1 and No. 3 (B3 can only be set to No. 1). In this case, the settings of No. 2 and No. 4 are disabled. The input data consists of the Parts Data (which is input by number and name or by Bit) as well as the X-axis and Y-axis coordinates (which are input by MDI or by teaching).

NOTE:

For information on selecting the corresponding bit for a part, please refer to Section 6-3, "Bit No. Specification."

d) Lateral Magazine Tray Unit

200.0

```
[Feeder Pos.: M2
                  Feeder: Magazine
```

No. X mm Y mm No. X mm Y mm 100.0 200.0 135.0 200.0 1 11 103.5 200.0 12 138.5 200.0 2 3 107.0 200.0 13 142.0 200.0 110.5 200.0 145.5 200.0 14 4 114.0 200.0 15 149.0 200.0 5 117.5 200.0 152.5 6 16 121.0 200.0 156.0 200.0 7 17 8 124.5 200.0 18 159.5 200.0 128.0 200.0 163.0 200.0 19 9 131.5 200.0 166.5 200.0 10 20

183			
	No.	X mm	Y mm
	21	170.0	200.0
	22	173.5	200.0
	23	177.0	200.0
	24	180.5	200.0
	25	184.0	200.0

No: 1]

(Screen 6-5)

Filename	MANUAL
Bit Pos.	X = 2.4 Y = 429.6
	Key Operations
f·1:Read	f.6 :AC Func.
f-2:Teach/B	ESC: Input SW.
f-3: Teach/S	/ :End
f-4: Delete	A 1940 54013
f.5: Page SW.	
X Pos.	

< Base Data >

No.	X mm	Ymm	Pitch	Bit
1	100.0	200.0	3.5mm	1
2				
3				
4				

* There are two kinds of lateral magazine tray unit (hereafter called "magazine"), one in which the space between parts is 3.5mm (50 parts per magazine) and one in which it is 7mm (25 parts per magazine). Four magazines can be specified for one unit. Data is input in the area called "Source Data" seen in the lower righthand section of Screen 6-5. If the AC function is activated, the expanded data in the lefthand section is calculated automatically. The source data of one unit is divided into four sections. The following is an explanation of the four sections:

Xmm, Ymm : The parts coordinates of the leftmost edge of the magazine case.

- Pitch : Select 3.5 or 7 (inputting "mm" is not necessary)
- : For information on selecting the corresponding bit for a part, please Bit refer to Section 6-3, "Bit No. Specification."

If even one item on any line of source data is left out, the automatic calculation (AC) function will not be possible. Also, by changing the input (ESC key), inputting by MDI and teaching is possible. (The input position can be switched from source data to expanded data and vice versa by using the ESC key.)

	[IC Tray]				
No.	X mm	Y mm			
1	10.0	10.0			
2	35.0	10.0			

60.0

85.0

110.0

135.0

160.0

185.0

210.0

235.0

10.0

10.0

10.0

10.0

10.0

10.0

10.0

10.0

3

4

5

6

7

8

9

10

No.	X mm	Y mm
11	10.0	30.0
12	35.0	30.0
13	60.0	30.0
14	85.0	30.0
15	110.0	30.0
16	135.0	30.0
17	160.0	30.0
18	185.0	30.0
19	210.0	30.0
20	235.0	30.0

No.

21

22

23

24

25

X mm	Y mm	Filename Bit Pos.	$\begin{array}{l} \text{MANUAL} \\ \text{X} = 2.4 \text{ Y} = 429.6 \end{array}$
10.0	50.0		Key Operations
35.0	50.0	f·1:Lo. File	f·6 :AC Func.
60.0	50.0	f·2:Teach/B f·3:Teach/S	ESC: Input SW. / : End
85.0	50.0	f-4: Delete f-5: Page SW.	
110.0	50.0	X Pos.	
			< Base Data >

Po	X mm	Y mm	Nx	10
0	10.0	10.0	Ny	5
x	235.0	10.0	Bit	3
Y	10.0	90.0	11	

It is possible to use a tray which holds a maximum of 50 parts. In the same way * as the magazine, it is necessary to input source data, and after inputting the data, the AC function can be used to obtain expanded coordinates. An explanation of each item of source data is found below:





- 0,X,Y : The coordinates for the bonding position of parts (shown at left) (input by MDI or teaching)
 - : The number of parts in the direction X
 - : The number of parts in the direction Y
 - : For information on selecting the corresponding bit for a part, please refer to Section 6-3, "Bit No. Specification."

If even one item on any line of source data is left out, the automatic calculation (AC) function will not be possible. Also, by changing the input (|ESC| key), inputting by MDI and teaching is possible. (The input position can be switched from source data to expanded data and vice versa by using the [ESC] key.)

f) Rotary Table Unit

The rotary table can be specified only at B3, and specification is only possible when declaring unit specifications. (It is not necessary to specify the coordinates.)

2. Explanation of Key Operations

f·1	See	Section	6-1-1	(page 6-2).	
(Lo	ad File)				

(Teaching/Bit)
 When this key is pressed, the teaching mode is entered, depending on the bit. Use the cursor key on the keyboard of the main unit to move the cursor to the desired position. Moving the bit up and down, determine the location where the part will be bonded or loaded. Press the "Teach" key on the main unit to memorize the coordinates of the position. If you want to cancel at any point, press the [f·2] key again.

f:3In contrast to the bit teaching of f:2, this function controls(Teaching/Spot)"spotlight" teaching, but the optical teaching unit is an option. If
you want to cancel at any point, press the f:3 key again.

NOTE:___

To input the following 5 parts supply positions: L1, L2, B1, B2 and B3 (see Page 6-1) by teaching, please use Teaching/Bit.

[f·4]	Move the	e cursor	to the	line that	t you	want to	delete	and	press
(Delete)	f·4. Th	e line wh	ere the	cursor is	s will	be delete	ed.		

f.5This function is used on the Magazine or IC Tray screens. Since(Page Switch)expanded coordinates can be displayed 25 at a time, pressing thef.5key will display expanded coordinates 1 to 25 and then 26 to 50 alternately.

f-6AC FunctionUsed to automatically calculate the coordinate positions of the
magazine or IC tray. Input the basic data, then press the |f-6| key.(Automatic

Calculation)

(End) When this is pressed, you return to the unit specifications screen. (End) Data is stored as a block on the unit specifications screen.

EXPLANATION OF BIT NO. SPECIFICATION

For this unit, when inputting Mount Data for the following items, for head chucking specifications (see 4,1),(3)), rotation operation other than the bit pattern (see 4,1),(2)) specification rotation is necessary for Mount Data Input, for centering of mini-mold transistors, mini-flat ICs, etc., along the wide direction of the chuck (left/right direction). However, for pa ts without leads, such as square chips, which are not affected by the chuck width, operation is changed depending on the bit number at the time feeder coordinates are specified, to avoid unnecessary operation.

Consequently, please specify bit numbers for those parts by referring to the chart below, which shows the correspondence between the parts and their bit numbers.

No.	Part	(Note 3) Bit No.	1	2	3	4	5	6	7	8	9
1	Square chip 2125		0								
2	. 3216		0	18							
3	3819		0	0							
4	4726			0							
5	6332			0							
6	7343			0							
7	MELF 1/16	w	0								
8	1/8 V	v	0								
9	1/4 V	v	0	0							
10	Mini-mold transistor									0	
11	Mini-power transistor				8						0
12	SOP 8P				0	-					
13	14P				0					1	
14	16P				0	1					
15	20P				0		(Note 2) O				
16	24P					1	0				
17	28P					(Note 1) O	0				
18	PLCC 18P						0				-
19	20p						0			1	
20	28P					(Note 1) O	0				
21	32p					0				1	
22	44P					0					
23	52p					0					
24	68P					0					
25	QFP 44P ~ 64P					0					
26											
27											
	Head operation pattern (Note	e 4)	A	А	B,C	A	B,C	A	A	B,C	B,C

Correspondence	Chart for	Parts and	Their	Bit Numbers
----------------	-----------	-----------	-------	--------------------

NOTE:__

9

- 1. If the width of the part (including the lead) is more than 11.4mm, please use Bit 4.
- 2. If the width of the resin is more than 6mm, please use bit 5.
- 3. Please use the following bit numbers for the bits listed below:

Bit No.	В	it Type
1	Bit 1	for small chips
2	Bit 2	for medium chips
3	Bit 3	for small SOP
4	Bit 4	for PLCC
5	Bit 5	for large SOP
6		
7		
8	Bit 1	for small chips

Bit 2 for medium chips

Nos. 6 and 7 are used for special designations.

4. The chart below shows the head operation pattern and the corresponding pattern for each unit and its specified position.

Pattern	Operation Specified by Mount Data	Operation Chart
	+90° + chuck	Right rotation → Picking → Left rotation → Chuck → Placing
A [-90° + Chuck	Picking \rightarrow Right rotation \rightarrow Chuck \rightarrow Placing
	Chuck	Picking \rightarrow Chuck \rightarrow Placing
	+90° + Chuck	Right rotation \rightarrow Picking \rightarrow Chuck \rightarrow Left rotation \rightarrow Placing
в	-90° + Chuck	Picking → Chuck → Right rotation → Placing
	Chuck	Picking \rightarrow Chuck \rightarrow Placing
	+90* + Chuck	Right rotation → Picking → Left rotation → Chuck → Placing
с [-90* + Chuck	Picking \rightarrow Right rotation \rightarrow Chuck \rightarrow Placing
I	Chuck	Picking \rightarrow Right rotation \rightarrow Chuck \rightarrow Left rotation \rightarrow Placing

Head Operation Pattern Chart

Operation Pattern for Each Unit and its Specification Position

Unit position Unit	F1	F2	B1	B2	B3	L1	L2	R1	R2	M1	M2
Bulk	Α	A	A	A	\square	A	A	A	A		
Tape (6)	С	С	С	С	\square	В	В			\square	
Tape (3), (4)	В	В	В	В	\bigtriangledown	C-1	C•1	\square	\square		
Magazine		\bigtriangledown		\square	\square	\bigtriangledown	\triangleright			В	В
Stick	/	\bigvee	С	С	С	\square					
IC Tray	/				\square				/	A	

* 1 These patterns cannot be set for the four tape feeders.



	[Place	ement	Data li	n]			
No.	F.Pos	BTT	HDC	RTT	AH	X mm	Y mm
1	RI- 1					100.0	100.0
2	R1-2	90	•			110.0	100.0
3	R1-3					100.0	110.0
4	LI- 1	- 90				150.0	150.0
5	M2- I					170.0	170.0
6	M2- 1					170.0	180.0
7	L2- 1		•			160.0	150.0
8	MI			45		150.0	200.0
9	МΙ			90		170.0	200.0
10	MI					190.0	200.0

Filename	MA	ANUAL	(12/12)			
Bit Pos.	x	$X = 2.4 \ Y = 429.6$				
PWB H.P.	х	= 0.0 Y = 0.0				
K	ey Operations					
f-1: Load File	f•7	: SCR Up				
f·2: Teach/B	f•8	: SCR Down				
f-3: Teach/S	f•9	: Bit Optim.				
f-4: Delete	f-1	f-10 : Step & Rep.				
f.5: Insert	ES	ESC: PWS H.P.				
f.6: Save	/ : End					
<	Feeder Pos	. 10-key >				
7(B1)	8(B2)	9(B3)				
4(L2)	5(M2)	6(R2)				
1(L1)	2(M1)	3(R1) = (D1)				
0(F1)	, (F2)					
Feeder Po	s.					

* A maximum of 2,000 mount coordinates can be memorized in one file. Under auxiliary operations, 2,000 points can be used to specify another bonding pattern, but in the case of paste solder, for example, you need to specify 64 points for the QFP of the 64 pins. An explanation of the input items at the lefthand side of Screen 7-1 is given below.

EXPLANATION OF INPUT ITEMS

1.

1. F.Pos (Feeder Position)

The position where the part will be bonded is specified by "Unit Number + (Rail Number)". However, for the IC Tray, only the unit number (M1) is necessary. The unit number is not input directly but input using the 10-key correspondence system illustrated below.

CLR	HELP		/
7	8	9	*
B1	B2	B3	
4	5	6	+
L2	M2	R2	
1	2	3	=
L1	M1	R1	DI
0		•	J.
F1	F2		

* The upper section of each key shows the keyboard symbol, while the lower section shows the unit number. However, "DI" shows the dispenser and is indicated when solder cream is used.

NOTE:

Please refer to Screen 6-1 (page 6-1) regarding unit positions.

2. BTT (Bit Turn)

This function turns parts $\pm 90^{\circ}$ and loads them. There are three types of commands:

0 : No turn + : + 90° - : - 90°

NOTE:_

To specify no rotation, either the return key or the cursor can be used. (The same applies to the following.)

3. HDC (Head Chucking)

When there is a need for special accuracy in loading parts, the centering adjust chuck attached to the head, or the rotary table, must be used for chucking. The commands for the centering adjust chuck are explained below.

There are two types of centering adjust chuck commands. For the rotary table, please refer to the description in the following section, "Rotary Table Turn".

4. RTT (Rotary Table Turn)

This function is used to rotate parts or for chucking. Parts are rotated in 15° notches, so specifications can range from 0 to 345°.

The commands are:

0	Not being used
15~345	: Rotate only the indicated value
*	: Chucking only

The rotary table is optional.

5. CM (Cement Pattern)

It is possible to specify items (1 to 40) memorized in auxiliary operations. The maximum offset position from the parts loading position is 8 points.

6. Xmm, Ymm (Parts Loading Positions)

These are coordinates for parts loading positions. Input by MDI or teaching.

NOTE:_

Even if a rotary table setting exists within a single unit of mount data, in the case that head chucking or rotation has been concurrently set, the rotary table will have priority and the settings of chucking and rotation will be disregarded.

2. ____

EXPLANATION OF KEY OPERATIONS

f-1See 6-1-1 (page 6-2).

(Load File)

(Teaching/Bit)

[f·3].....See 6-2-2 (page 6-7).

(Teaching/Spot)

[f:4]With this function, data can be deleted no matter what screen you(Delete)are on, by specifying the line number or numbers that you want to delete.

Ex) Delete Line 1 🖌 or Delete Lines 1-3 🖌

f.5Move the cursor to the place where you want to insert a line and press(Insert)the f.5 key. One line will be opened up. At that position, the cursor
Cannot be moved to any other position until data has been input or



(Screen Up)

4. RTT (Rotary Table Turn)

This function is used to rotate parts or for chucking. Parts are rotated in 15° notches, so specifications can range from 0 to 345°.

The commands are:

0	: Not being used
15~345	: Rotate only the indicated value
*	: Chucking only

The rotary table is optional.

5. CM (Cement Pattern)

It is possible to specify items (1 to 40) memorized in auxiliary operations. The maximum offset position from the parts loading position is 8 points.

6. Xmm, Ymm (Parts Loading Positions)

These are coordinates for parts loading positions. Input by MDI or teaching.

NOTE:_

2..

Even if a rotary table setting exists within a single unit of mount data, in the case that head chucking or rotation has been concurrently set, the rotary table will have priority and the settings of chucking and rotation will be disregarded.

EXPLANATION OF KEY OPERATIONS

f·1	See 6-1-1 (page 6-2).
(Load File)	
f·2 (Teaching/Bit)	See 6-2-2 (page 6-7)
[f⋅3] (Teaching/Spot)	See 6-2-2 (page 6-7).
f·4 (Delete)	With this function, data can be deleted no matter what screen you are on, by specifying the line number or numbers that you want to delete. Ex) Delete Line 1 or Delete Lines 1-3
[f·5] (Insert)	Move the cursor to the place where you want to insert a line and press the f.5 key. One line will be opened up. At that position, the cursor Cannot be moved to any other position until data has been input or the line deleted.
[f·6] (Save)	See 6-1-1 (page 6-2).
[f⋅7] (Screen Up)	Advances the text on the screen by units of one page (scrolling).
[f⋅8] (Screen Down)	Moves in reverse order in units of one page (scrolling).

[f.10]In the case of a cracked assembly board, etc., if master data only is(Step & Repeat)created, if you input the x, y direction of the space between assembly
boards and number of boards, the complete mount data can be created.

If correct data is input for each of the items shown below, by drawing on the master data, coordinates will be developed for the pitch and number of items in x and y.

(Example)

(End)

	7	8	9
Yn = 3 <	4	5	6
↓ ↓ ↓	1 Master	2	3
ιL	Xp		

- Xp : The X direction master assembly board size or space between parts identical to that of adjoining board
- Yp : The Y direction master assembly board size or space between parts identical to that of adjoining board
- Xn : Number of copies of the X direction including the master board

Yn : Number of copies of the Y direction including the master board

Press to terminate.

When this key is pressed, the message "Do you want to save? (Y/N)" appears. To save, press "Y"; otherwise press "N". If a different key is pressed, the operation will continue without being terminated.



	** Pro	duct >	**				
No.	F.Pos	BTT	HDC	RTT	AM	X mm	Y mm
1	R1-1					100.0	100.0
2	R1-2	90	•			110.0	100.0
3	R1-3					100.0	110.0
4	L1- I	- 90				150.0	150.0
5	M2- 1					170.0	170.0
6	M2- 1					170.0	180.0
7	L2- 1		•			160.0	150.0
8	MI			45		150.0	200.0
9	MI			90		170.0	200.0
10	MI			•		190.0	200.0

Filename	MANUAL	(12/12)			
Bit Pos.	X = 2.4 Y = 429.6				
PWB H.P.	X = 0.0 Y = 0.0				
	Key Operations				
f-1: Load File	f.6: Save				
f-2: Teach/B	f·7: SCR. Up				
f-3: Teach/S	f.8: SCR. Down				
f-4: Exec.	f.9: Prod. Cond.				
f.5: Stop	/ : End				
1.9. 9rop	/ : Elig				
Prod. Mode		٦			
Prod. Mode	: Mount : Off	٦			
Prod. Mode Conveyor	: Mount : Off]			
Prod. Mode	: Mount : Off				
Prod. Mode Conveyor Re-pick	: Mount : Off				

(Screen 8-1)

* Based on unit data and mount data, parts are loaded and bonded on the assembly board. The chart on the left side of Screen 8-1 provides a reference for data. Data cannot be altered here. However, during Step Operation, changes are possible when the activate command is issued (at each interrupt position) for teaching.

EXPLANATION OF KEY OPERATIONS

[f·1].....See 6-1-1 (page 6-2). (Load File)

[f·2].....See 6-2-2 (page 6-7). (Teaching/Bit)

[f·3].....See 6-2-2 (page 6-7). (Teaching/Spot)

f·4This activates production (including after a temporary interruption).(Execution)The production process is shown below.



If the process is interrupted, the message "1: Continuous 2: Step" appears. It is possible to change from continuous operation to step operation while the production process is underway.

After each step operation, bit change, IC tray or magazine exchange, press [f-4] to continue.

Operation Procedure for Step Activation



f·5	
(Stop)	If you want to halt production completely, press it twice. To continue after a temporary interruption, press the $f \cdot 4$ (Activation) key.
[f·6]	See 6-1-1 page 6-2. During production in the Step mode, if teaching

T·D	
(Save)	took place and the coordinates were changed, data is saved with this
	function.

f·7	Advances the data by one screen (scrolling).
(Screen Up)	
f·8	
(Screen dov	vn)
[f·9]	Setting conditions appropriate for production.
(Production	Conditions)

Prod. Mode:	1. Place 2. Adhe. 3. Sold
Conveyor:	1. on 2. off
Repick:	1. on 2. off (Number of retries up to 9 times)
Prod-Count:	4 digits (≤ 9999)

To terminate, press the f.9 key again.

7

......Press to terminate.

(End)

When this key is pressed, the message "Do you want to save? (Y/N)" appears. To save, press "Y"; otherwise press "N". If a different key is pressed, the operation will continue without being terminated.

2.2



(Screen 9-1)	
--------------	--

 I/O Test	
1. Input Check	
2. Head	
3. X-Y Movement	
4. R Table	
5. Automatic Conveyor	
/. End	
Please select a number.	

Activates a simple I/O test.

INPUT CHECK

1..

Input Check]				
Item	Input	Item	Input	Item	Input
HEAD	off	- Y	off	HOME	off
VAC.	off	+ Y	off	R.T (CTR)	off
TEACH	off	- X	off	R.T (CW)	off
FAST	off	+ X	off	R.T (CCW)	off

Push Keys of each Item

/ : End

Check the input conditions (conductive conditions) of the main keyboard, HOME key, and rotary table switch. Normally "OFF" is displayed but if a key is pressed "ON" is displayed during that time only.

Head]	(Screen 9-3)					
Item	P. key	Out	In			
UP/DOWN	f • 1	off	off			
Rotate	f • 2	off	***			
Vacuum	f · 3	off	off			
T. Knock	f·4	off	***			
Centering	f • 5	off	***			
Dispenser	f · 6	off	***			

ESC : Stop / : End

- * The simplex operation of the centering adjust chuck takes place as a result of the up and down movement, rotation, vacuum and tape knock of the bit of the head section. (Alternately ON and OFF) The dispenser's operation is one-shot. The UP/DOWN of the "Input" of Illustration 6-3 is effective only for the dispenser head. Vacuum is sensed by the vacuum sensor.
- X-Y MOVEMENT

(Se	creen 9-4)	
[X	-Y Move]	
f·1	: HOME	
f·2	: Exec.	
ESC	: Stop	
1	: End	

NOTE:

3.

The HOME key of $f \cdot 1$ causes a return to the starting point of the machine.

* The X-Y axis moves continuously in the pattern shown at the right. (1 to 10) Operation can be interrupted at any point from A to D by using the ESC key.



4.

ROTARY TABLE

R·Table]	(Screen 9-5)					
ltem	F.Key	Out				
CW(180°)	(·1	off				
CCW(180°)	f · 2	off				
Centering	f·3	off				

^{/:} End

A simple check of rotary table operation occurs.
 Three kinds of operation are possible: a 180° rotation towards CW, a 180° rotation towards CCW, and centering (chucking).

5

AUTOMATIC CONVEYOR

[Conveyor]	(Sc	reen 9-6)		
Item	F.Key	Out	Item	In
Conveyor Motor	f·1	off	Pass Detect(In)	off
Stopper	f • 2	off	PWB Detect	off
Centering Pin	f·3	off	Center.Pin Conf.	off
Support	f·4	off	Ready In	off
Ready Out	f·5	off	Pass Detect(Out)	off

/: End

- * The operation check of each mechanism of the automatic conveyor is displayed, along with the input conditions of its accompanying sensor.
- * If an automatic conveyor is not attached, "ON" is displayed for transition detection (in) and transition detection (out). This does not signify a problem.



(Screen 10-1)
Sub Menu
1. Component Data
2. Adhesive Pattern
3. Delete File
4. Print Data
5. Prod. Inform.
/. End
Select No.

* The five kinds of operations listed above take place under Auxiliary Operations.

PARTS DATA

1.

No.	Name	Size	в	No.	Name	Size	В	No.	Name	Size	В	No.	Name	Size	B
1	2125	2.0	1	9				17				25			L
2	3216	3.2	1	10				18				26			L
3	MLF16W	1.6	1	11				19				27			L
4	MLF8W	2.0	1	12				20				28			
5	MLF4W	5.9	2	13	a.			21		1	Н	29	-	1	t
6	SOP8P	6.0	3	14				22				30		1	t
7	SOP16P	12.5	3	15			П	23			Π	31		-	t
8			Π	16				24				32		1	t

At this time, if NO. 1-32 were stored as Name information, the name will take priority over the number.

1. Explanation of Key Operations

A maximum of 32 items of parts data Can be stored. The procedure by which data is Start Move the cursor to the number you want to input. Input the name Seven letters or less Between 0.1 and 30.0 (the long side of the Input the size. element) For information on selecting the corresponding bit Input the bit type for a part, please refer to Section 6-3, "Bit No. Specification. End

f-4See 7-2 (page 7-2). (Delete)

| /]Data is automatically saved upon termination. (End)

CEMENT PATTERN

2.

** Adhesive Pattern ** < Registration > (Screen 10-3) 17: 9: 13: 5: I: 14: 18: 10: 2: 6: Table 10-1 19: 15: 7: 11: 3: 4P 20: 12: 16: 4; 8: < No: 3/ Name: 4P > 7 8 6 5 3 4 1 2 Point X of mm Table 10-2 Y of mm ESC: Call/Return f · 4 : Delete < Key Operations > f • 5 : Page SW. f · 2 : Regist. : End Name

For bonding points, a value with a maximum of 8 points and 40 patterns offset from the parts loading position can be stored. (The input range is from -15.0 to +15.0.) *

10-2



1. Component Data
A 1 11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
2. Adhesive Pattern
3. Delete File
4. Print Data
5. Prod. Inform.
/. End

* The five kinds of operations listed above take place under Auxiliary Operations.

PARTS DATA

1..

No.	Name	Size	В	No.	Name	Size	B	No.	Name	Size	В	No.	Name	Size	B
1	2125	2.0	1	9				17				25			
2	3216	3.2	1	10				18				26			
3	MLF16W	1.6	1	11				19				27			Γ
4	MLF8W	2.0	1	12				20				28			Γ
5	MLF4W	5.9	2	13				21				29	3		Γ
6	SOP8P	6.0	3	14			\square	22				30			
7	SOP16P	12.5	3	15				23				31			
8				16		1.1		24				32			F

* At this time, if NO. 1-32 were stored as Name information, the name will take priority over the number.

Table 10-1 of Illustration 10-3 shows the save conditions for patterns. When the cursor is here, the pattern name can be stored or the pattern deleted. To call a pattern, align the cursor with the number of the pattern you want to call, and press the **ESC** key. The pattern contents will be displayed as shown in Table 10-2, and the cursor will also move to the chart. At this point you can make changes in the pattern, and the pattern can be stored, but if you delete, the X and Y coordinates of the position where the cursor is will be deleted.

1. Explanation of Key Operations

[ESC] (Call/Return)	Align the cursor with the pattern you want to call, and press the <u>ESC</u> key. The pattern will be called to Table 10-2. If there is no pattern memorized in the indicated location, press the <u>ESC</u> key again to return the cursor to Table 10-1.
f·2 (Save)	When the cursor is on Table 10-2, if you press the f-2 key, a Memory Number will be asked for (from 1 to 40). Input the number you want to store and it will be saved.
[f·4] (Delete)	 See 6-2-2 (page 6-7). On Table 10-1, the pattern at the cursor location will be deleted. On Table 10-2, the offset values for X and Y at the cursor location will be deleted.
f·5 (Page Switch)	When the cursor is on Table 10-1, if you press the f.5 key, patterns 1 to 20 and 21 to 40 will be displayed alternately.
[/] (End)	Returns to the Sub-Menu. When this is pressed, data is automatically saved.

3..

FILE DELETION

	File Dire	ecto	ry
1	: AO1	7	: SOP1
2	: AO2	8	: XX
3	: SOP	9	: KAZ
4	: MANUAL	10	: CHACK
5	: INA	11	: ROT
6	: TETSU	12	: CENTER
<	Delete File >		
Se	lect No. (, : E	nd)	

Screen 10-4

* On the Sub-Menu screen, when file deletion is activated, the directory screen appears. Input the number of the file that you want to delete. After a confirmation message appears, the file is deleted. Press the "" // " key to terminate and return to the Sub-Menu.

Data output

Connect up a printer which has a centro parallel interface. Five items can be output; unit data, mount data, parts data, bonding data and production management information. When any of these items is selected in Auxiliary Operations, screen 10-5 is displayed.

Fi	le Directory	
1: PROG 1	7:	
2: PROG 2	8:	
3: PROG 3	9:	
4: MANUAL	10:	
5:	11:	
6:	12:	
< Feed	er (ESC : Item)>	
	t No (/ : END)	

a) Explanation of operation

In the case of unit data, mount data and production management information, input the file number you wish to output. For parts data, in the case of bonding press CR only (carriage return key) (output items are set with the <u>ESC</u> key). The required data are read in accompanied by a READING IN display. At the end of a read-in, a Y/N execution check message appears on the screen. If you want to terminate "Y" during execution, input an "N". If a "Y" is input, data is output to the printer and an OUTPUT message appears on the screen. If you want to terminate this operation press the <u>F5</u> key (to clear data already stored in the printer's buffer, switch OFF the power to the printer and then switch ON again).

NOTE:_

If data is output when the printer is disconnected, an error message from the internal OS (operating system) of the PC remains on part of the screen. In this case, end the operation and connect up the printer.



c) Output example

***	******	*****	Feeder	2	*******	******
File	ename :	MANUAL				
Feed	ler pos.	.: B1	Feed	er : S	tick	
No	Kind	Comp.Data	Size	Bit	X mm	Y mm
1	STD.	6:S0P8P	6.0	3	19.5	495.3
2	STD.	6:S0P8P	6.0	3	51.5	495.3
3 4	WIDE.	7:SOP16P	12.5	3	100.5	498.5
Feed	ler pos	.: R1	Feed	er : L	inear	
No	Kind	Comp. Data	Size	Bit	X mm	Y mm
1	****	1:2125	2.0	1	356.1	145.5
2	****	2:3216	3.2	1	356.7	159.5
3	****	3:MLF16W	1.6	1	355.9	173.5
4	****	4:MLF8W	2.0	1	356.1	189.5
5	****	5:MLF4W	5.9	2	358.0	201.5
6	****					
7	****	:				
8	****	:				
9	****					
10	****	:				

Placement

Filename : MANUAL

rite	Hame .	IANOAL		4.1			
No	F.Pos	BTT	HDC	RTT	AH	X mm	Y mm
1	R1 - 1					100.0	100.0
	R1-2	90	*			110.0	100.0
2 3	R1- 3					100.0	110.0
4	L1- 1	-90				150.0	150.0
5	M2-1					170.0	170.0
6	M2 - 1					170.0	180.0
7	L2- 1		*			160.0	150.0
8	M1			45		150.0	200.0
9	M1			90		170.0	200.0
10	M 1			*		190.0	200.0

d) Interface and Character Code Set

(1) Printer Interface of PC-8801 FH30

Signal Pin No.	Signal	Direction	Description
1	PSTB	OUT	PSTB pulse to write data out
2	PDB0	OUT) .
3	PDB1	OUT	
4	PDB2	OUT	
4 5	PDB3	OUT	TTL, Data outputs to printer
6	PDB4	OUT	8 bit parallel data
7	PDB5	OUT	
8	PDB6	OUT	
9	PDB7	OUT)
10	NC		
11	BUSY	IN	"LOW" level is printer ready.
12	NC		and a second sec
13	GND		
14	GND		

PRINTER



(2) Character Code Set of PC-8801 FH30

				001	unnin	(50,									
	0	1	2	3	4	5	6	7	8	9	Α	В	C	D	Ε	F
0		D _E		0	(a)	Р		p		Т		_	9	111	-	Х
1	s _H		!	1	A	Q	a	q		Т	0	7	チ	ム	F	円
2		D ₂		2	B	R	b	r		Η	r	1	ッ	X	+	年
3		D ₃	#	3	С	S	с	s		F	J	ウ	Ŧ	ŧ	Т	月
4			\$	4	D	Т	d	t		-		J.	ŀ	ヤ		日
5	EQ	NK	%	5	E	U	e	u		-	•	才	ナ	ユ		時
6	AK	S _N	&	6	F	v	f	v			ヲ	力		E		分
7	BL	EB	,	7	G	w	g	w			7	キ	R	ラ	V	秒
8	BS	C _N	(8	H	x	h	x		Г	1	ク	ネ	IJ	٠	
9	H _T	EM)	9	I	Y	i	у		Г	ウ	ケ	1	ル	۷	
Α	L _F		*	:	J	Z	j	z		L	I	コ	\mathcal{N}	V	٠	
B	HM	EC	+	;	K	[k	{	4		オ	#	Ł		*	
с	C _L	+	,	<	L	¥	1	-	200	1	+	シ	フ	ワ	•	
D	CR		-	=	M]	m	}		2	ュ	ス	~	ン	0	
E	s _o	1		>	N	^	n	~		1	F	セ	ホ	•	/	
F	s _I	Ļ	1	?	0	-	0		+	1	Ÿ	ソ	7	0	\backslash	

Column (MSB)

NOTE:____

The code of character "A" is 41 H

5.

Production Management Information

The quantity of parts loaded and of parts missed during production are counted for each feeder. At this part of the program, that data (excluding, however, the data on cement and cream solder) can next be displayed on the screen then initialized. To perform output, select "Data Output" of Auxiliary Operations.

Condition: "The count of production management information can be performed for entire range of executable data, but only in the case of continuous execution." In other words, in the case of partial loading or during step execution, the production management information involved will be ignored by the counter. If step execution is performed or execution is cancelled after the above condition has been met, however, the production management information concerned will be counted by the counter.

The menu will initially be set to "Display," but can be switched to "Initial" by pressing the <u>ESC</u> key. (The "Display"/"Initial" setting can be alternately switched by pressing the <u>ESC</u> key.) When a file number is input in "Display" status, the contents of the selected file are displayed in chart form. When a file number is input in "Initial" status, that file's contents will be initialized.

1: PROG 1	7:	
2: PROG 2	8:	
3: PROG 3	9:	
4: MANUAL	10:	
5:	11:	
6:	12:	
< Disp	lay (ESC: Item))	
	No. (/: END)	

(Screen 10-6)

a) Screen display

By pressing the <u>ESC</u> key and setting the status to "Display," the quantity of parts picked and of parts missed can be displayed in chart form. After inputting a number to select the desired file, the quantity of parts picked is displayed first. To display the quantity of parts missed, press the <u>ESC</u> key. (The two charts can be alternately selected by pressing the <u>ESC</u> key.) To end the "Display" status, press the <u>/</u> key.

(1) Screen for parts picked Screen 10-6-1

Fi	le nam	e: MANUAL		Count: 5			<placement></placement>	
	FI	F2	B1	B 2	RI	R2	LI	L2
			Stick (S)		Linear		Tape (6)	Tape (3)
1			100		50		50	25
2			100		50		50	0
3			100		0		0	0
4			100		0		0	
5					0		0	
6					0		0	
7					0			
8					0			
9					0			
10					0			

	MI		M2
	Tray		Magaz.
1		20	40
1 2 3 4			0
3			0
4			0
_	B3		
1 2			

(ESC : Charge, / : END)

(2) Screen for number of parts missed Screen 10-6-2

FI	F2	BI	B2	RI	R2	LI	L2		MI	M2
		Stic (S)		Linear		Tape (6)	Tape (3)		Тгау	Magaz.
1 2 3 4		0002		1 0 0				0 1 0 2 0 3	1	
5				0		0			B3	
7 8 9				0						
10		1		0					2	

(ESC : Change, : END)

b) Initializing files

This job initializes a file that contains production management information. Press the $[\underline{ESC}]$ key to switch the setting to "Initial", then input the number of the file you wish to initialize. The "Sure? (Y/N)" message will appear next, so press "Y" to execute initialization or "N" to cancel it.

c) Handling the Production Management Information

The production management information is designed to be processed in daily batches. Therefore, after outputting the data once a day, always make sure to initialize the data. Moreover, please note that the maximum count value for each data type is "60,000" and that the counter will return to "1" if this count is exceeded.

MISCELLANEOUS 11

POINTER FUNCTION

1.

2.

When you want to call mount data specified at mount data input or production, input "P (No)". The data will be displayed at the top of the screen, starting with the specified number. On the last line, "P*" will be displayed. If "P" is input, the first line is displayed.

DISK FORMATTING

If there are two disk drives, use the following procedure for formatting (Formatting Procedure for Drive 2).

- (1) Confirm that A> is displayed on the screen.
- (2) Insert the new disk that you want to format in Drive B.
- (3) Next, type in FORMAT and press the 🖌

A > FORMAT

(4) The following message appears on the screen.

Format Utility Program Ver. 1.0 ** Format Mainmenu **

- A. Exit to CP/M.
- B. Select disk. Current is B:
- C. Format selected disk.

VARNING - Formatting destroys any data on the disk.

Your selection?

- Use A to return control to the CP/M.
- B selects the disk upon which the operation will be performed. Drive B is currently indicated.
- Select C to go ahead with the formatting operation on the indicated disk.
- "Your selection?" indicates that you should type A, B, or C, whichever you have chosen.

(5) At this point, type in C.

(6) The following message is displayed on the screen.

Format Utility Program Ver. 1.0 Formatting PC-80S31/32 drive=8:

A. Exit to the ** Format Mainmenu **
B. Format this disk.

Your selection?

- Use A to return to the main menu.
- Use B to indicate the formatting operation.
- (7) Type in B.
- (8) The following confirmation message appears. Type in Y (Yes). If you type in N (No), the screen returns to the screen in (6).

Your selection? B

Sure (Y/N)?

- (9) When you type in Y, you will hear a clicking sound. The formatting process is beginning, when it ends, the message in (6) is displayed again.
- (10) If you want to format another new disk, substitute the new disk for the already-formatted disk in Drive B, and type in B. The process repeats from (8).
- (11) When the message in (4) is displayed again, to return control to the CP/M type in A.
- (12) The system will wait for CP/M commands, and the prompt A > will be displayed.

3. SYSTEM AND DATA DISK BACKUP

If there are two drive units, use the following procedure:

First, insert the CP/M system disk in Drive A, and press RESET.

 Check that "A>" is displayed on the screen (this is called the "prompt A>"). Right behind the prompt A>, type in "BACKUP" and press the key.

A>BACKUP

(3) The following message appears on the screen: Please mount SOURCE disk on drive A:

hit RETURN if you are ready.

(4) At this point, insert the disk that you want to copy (the source disk) in Drive A, and press the key.

(For a CP/M backup, the source disk is the CP/M master disk, so it doesn't matter if you don't insert a floppy disk at this point.)

- (5) The following message is displayed: Please mount DESTINATION disk on Drive B: hit RETURN if you are ready.
- (6) Insert a formatted disk in Drive B, and press the key.
- (7) There will be a clicking sound, and the disk copying operation begins. At this time, whenever one track is finished, a dot is displayed. The dots line up next to each other as tracks are copied.

- (8) When the copying operation is finished, the following message is displayed: Complete.
 - Hit RETURN to do it again, hit [^]C to return to CP/M.
- (9) If you want to copy onto one more disk, press the key.
 The screen returns to step 3, and you can repeat the procedure beginning with step 4.

If you are finished copying, press CTRL C.

(10) When CTRL C is pressed, control returns to the CP/M. The system is waiting for CP/M commands to be input and the prompt A> is displayed.

OPERATION INDICATIONS AND PRECAUTIONS

- (1) When the number of stored files reaches 12, the message "DISK full !" will be displayed at the top of the Unit Data, Mount Data, and Production Screens. To create and save new data, data must be erased under auxiliary operations, or a new data disk substituted and the reset button pressed, or, if you want to reference data and start production, press CR (Carriage Return) to go ahead with normal operation, with no changes.
- (2) If you tried to save data in Mount Data Input but there is ineffective data, that line number is displayed once, up to 8 digits. Correct the data on the relevant line number and store it again.
- (3) When spot teaching, discrepancies may appear as shown in the illustration when compared with bit teaching, and there are occasions when spot teaching of feeder coordinates becomes impossible (especially for the values of L1, L2, B1, B2, and B3). In these cases, please use bit teaching. (Refer to Fig. 11-1).



(4) If changes were made in parts data input through auxiliary operations, the changes are not automatically mode in the parts data input section of "Unit Dta Input" after drawing up th data is completed. Therefore, it is necessary to make the changes once again in this section.

- (5) At Unit Data Input and Mount Data Input, teaching is possible via bit and spot, but not via dispenser head. At production, if mounting was done in Production mode, teaching via bit and spot is possible, and if soldering was done, teaching via dispenser head is possible. However, teaching is not possible in Cement mode.
- (6) Regarding the display of data by this system, in case any data has been set to a value outside of its permissible range, the data concerned will either be ignored or not displayed.
- (7) After inserting another disk during the operation of this system, always make sure to press the Reset switch at the bottom left of the computer to reboot the system. If you insert another disk then attempt to write data to it without first having reset the system, the Operating System will display an error message (Bdos error on A(B):) and program execution will stop.

If this happens, press the Reset switch to reboot the system, then repeat the writing operation once more.

- (8) When reading or saving a data file, numbers and characters other than 1 12 (01, 001, etc. are treated the same as 1) are handled as names if specified as file numbers. (However, effective file names may consist of up to 8 alphabetic characters only.) If 12 files have already been stored, be careful with name or number designation, since only the numbers 1-12 are effective file names when reading out and writing into files.
- (9) There may be cases where pressing DEL on the personal computer (PC-8801 FH) which controls the KP-350 causes the display to disappear. This does not affect operation.



Juki Automation Systems, Inc. 507 Airport Blvd. Morrisville, NC 27560 Telephone 919-460-0111 Fax 919-469-0480

Juki Automation Systems, Inc. 48531 Warm Springs Blvd. Suite 405 Fremont, CA 94539 Telephone 510-249-6700 Fax 510-249-6710